

Relationships between tree sparrow *Passer Passer montanus* fledging success and the quantity and quality of agricultural habitats – a model comparison study

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1 **Relationships between Tree Sparrow *Passer montanus* fledging success and the quantity**
2 **and quality of agricultural habitats – a model comparison study.**

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10

11 **Abstract**

12 Changes in land use due to agricultural intensification are a key anthropogenic cause of
13 biodiversity declines impacting invertebrate, plant and bird populations. This study assesses
14 whether fledging success in the tree sparrow, a farmland bird that has declined by over 94%
15 since 1970, is best described by patterns of agricultural habitat coverage or by the quality
16 (measured by invertebrate chick food abundance) of these habitat patches. We were
17 particularly interested in the effect of agri-environment scheme (AES) habitats on
18 reproductive success, as AES include habitat prescriptions that are employed to alleviate
19 biodiversity problems. Our results indicated that the habitat coverage model best fitted the
20 fledging success data and estimates from this model show that fledging success decreased
21 with the area of wild bird seed mix and grassland cover within the average adult foraging
22 range. Habitat coverage models are currently the most popular method of investigating AES –
23 bird relationships and our findings provide support to such studies. These models could be
24 used to assess whether AES farmland bird conservation strategies are successfully improving
25 reproductive success.

26

27 **1. Introduction**

28 To study the way in which habitat change may be influencing a species' decline, it is usually
29 necessary to make an assessment of habitat quality. Many studies that seek to do this rely on
30 simple measures of habitat quality based on the extent, or abundance, of certain habitat
31 features rather than a measure based upon qualitative traits, such as the resources the habitat
32 provides. Using more representative measures of habitat quality should increase the
33 effectiveness of conservation strategies derived from such studies.

34

35 Agricultural intensification is considered responsible for widespread biodiversity losses,
36 amongst a variety of taxa including invertebrates e.g. marsh fritillary *Euphydryas aurinia* and
37 small blue *Cupido minimus* butterflies (Fox et al., 2015), along with parallel declines in bird
38 species associated with farmland e.g. ciril bunting *Emberiza cirilus* and Eurasian stone curlew
39 *Burhinus oedicephalus* (Peach et al., 2001; MacDonald et al 2012). Agri-environment schemes
40 (AES) are designed to mitigate against such losses and are targeted so that landowners can
41 undertake management relevant to local environmental priorities (Natural England 2013a;
42 2013b).

43

44 Many studies of AES use substrate composition variables as a measure of habitat quality, but
45 do not assess whether the intended resources are being provided (e.g. Baker et al., 2012;
46 Bradbury and Allen, 2003; Bright et al., 2015; McHugh et al., 2016a). Alternatively, studies
47 take simple measures of resource provision (e.g. food abundance, prey and predator visibility;
48 Atkinson et al., 2004; 2005) but rarely weight habitats based on these measurements (but see
49 Ponce et al., 2014). It is possible, however, that the relationship between a species and their
50 habitat is best described by combined habitat extent - resource measurements i.e. in terms of
51 functional space (Butler and Norris., 2013). In the context of AES, monitoring habitat quality
52 effectively and appropriately is particularly important, due to the huge financial investment
53 made across the European Union (€34.5bn for 2007 – 2013; IEEP, 2008). For farmland birds
54 it is essential to ensure that once AES habitats are in place birds are receiving the benefits,
55 such as cover from predators, accessible prey and abundant food, that the habitats are
56 designed to provide.

57

58 The main aim of this study was to investigate how Eurasian tree sparrow *Passer montanus*
59 (hereafter tree sparrow) fledgling success, a measure of reproductive success, responds to
60 both simple habitat models and those that are weighted by a measure of resource provision, in
61 this instance in terms of food availability. The predictive power of models were compared
62 using an information theory approach and to our knowledge it is the first example of a study
63 that compares reproductive success models based on simple habitat measurements to those
64 describing functional space.

65

66 **2. Methods**

67 **2.1 Study Sites**

68 Fieldwork was conducted across the Marlborough and Pewsley Downs, Wiltshire, UK. Nest
69 box monitoring took place on 11 farms and within these farms, groups of nestboxes were
70 defined as breeding colonies when separated from the nearest alternative group of nest boxes
71 by 400 or more meters (n=23). The habitats available to tree sparrows inhabiting nest boxes
72 were grouped into 5 categories representing structurally similar feeding habitats; winter
73 cereals (winter wheat, winter barley), grassland (permanent and temporary grassland), oil-
74 seed rape, grass AES (2m, 4m and 6m arable grass margins, wildflower margins, pollen and
75 nectar margins, grass field corners) and wild bird seed mixture (WBSM).

76

77 Habitats were mapped using ArcGIS version 10.2.1 (ESRI, 2015) to calculate the surface area
78 of land used within 80m of occupied nest boxes. We choose to map habitat within 80m's of
79 nestboxes as adult tree sparrows are known to collect food for their chicks between 20 and
80 200m from their nests (Deckert, 1962), but their average foraging distance is 80m (Summers-
81 Smith, 1995).

82

83 **2.2 Food availability**

84 During July 2013, two sweep samples were taken from winter wheat, winter barley,
85 permanent and temporary grassland, oilseed rape, 2m, 4m and 6m arable grass margins,
86 wildflower margins, pollen and nectar margins, grass field corners and wild bird seed mixture
87 habitats when present within the foraging range of a tree sparrow colony (table 1). Where
88 more than one replicate of these habitats was available to a colony the replicate to be sampled
89 was randomly chosen using R. Random points within these habitats were chosen as sampling
90 locations using ArcGIS v10.2.1.

91

92 Sweep netting was used to take invertebrate samples as it is quick and samples are easy to
93 process. Samples comprised ten 180 degree sweeps, covering a distance of approximately
94 10m and a width of 2m. There are however, some limitations relating to this method
95 including the variance in sampling efficiency relating to habitat type sampled and variation in
96 the species recorded depending on their vertical distribution (Southwood, 1987).

97

98 Invertebrate abundance was also estimated for each habitat type using Vortis (Burkard
99 Manufacturing Co. Ltd.) suction samples, using samples that were collected from three farms
100 as part of a separate study (table 1; McHugh et al., 2016a). The Vortis Suction Sampler
101 (Burkard Manufacturing Co. Ltd.) has a suction area of approximately 0.08m². Three samples

102 were taken from each component habitat at 20 m intervals this sampling regime was chosen
103 due to a combination of time and weather constraints. Each of these three samples was made
104 up of 5 sucks lasting 25 seconds each, the nozzle pressed to the ground and samples therefore
105 covered a total area of 0.4 m².

106

107 Both sweep net and Vortis suction samples were stored in plastic bags for freezing before
108 being sorted for identification. Debris was removed from samples before storing them in 70%
109 alcohol. All tree sparrow chick-food invertebrates >2mm long were identified, namely the
110 sum of Araneae, Carabidae, other adult Coleoptera, coleopteran larvae, Diptera, Lepidoptera
111 larvae and Tipulidae (McHugh et al., 2016b); smaller individuals were not identified as they
112 do not constitute an important part of farmland bird diet (Westbury et al., 2011).

113

114 Habitat extent data (extracted from ArcGIS) was weighted by calculating the abundance of
115 invertebrates collected via suction sampling and sweep netting abundance per m² and
116 multiplying this by the total area of each habitat category.

117

118 **2.3 Bird Data**

119 Data on tree sparrow fledging success was recorded during the summers of 2013 and 2014.
120 Nest boxes were monitored every 2-3 days and for each brood we recorded both the number
121 of chicks which fledged successfully and the number that did not.

122

123 **2.4 Generalized Linear Mixed-effects Model (GLMM)**

124 Statistical analysis were conducted in R, v3.2 (R Core Development Team, 2015). In order to
125 determine whether fledgling success could be best explained by simple habitat area
126 measurements or by a measure of invertebrate food abundance we used a series of
127 generalized linear mixed effects models (GLMM) with binomial error distributions. The
128 LME4 package was used to build GLMMs with the GLMER function (Bates et al., 2015). An
129 information theory approach was taken to identify the optimal model that describes tree
130 sparrow fledging success (Burnham and Anderson, 2002). When using this method a series of
131 models are specified and are compared based on AIC weights. Four models were compared a
132 1) null model, 2) habitat extent model, 3) habitat extent weighted by sweep net invertebrates
133 and 4) habitat extent weighted by Vortis invertebrates. Each model contained the nested
134 random effects structures Farm/Colony/Year and Nest Box ID/Brood.

135

136 **3. Results**

137 Our habitat extent model revealed a significant negative relationship between fledging
138 success and the surface area of WBSM and grassland habitats (table 2). In contrast, neither
139 the sweep-net or Vortis weighted functional space models revealed significant habitat – bird
140 relationships (table 3).

141

142 Model comparison via an information theory approach revealed that tree sparrow fledging
143 success could be best explained by our habitat extent model, which had the highest Akaike
144 weight, valued at 0.751. This was followed by the null model which received a weighted
145 value of 0.103. The sweep net weighted and Vortis weighted food models were least
146 successful at explaining the relationship between fledgling success and the environment with
147 values of 0.079 and 0.067 respectively. An Akaike weight of 1 signifies that a model is
148 supported unequivocally over the other candidates. Consequently, this indicates that if
149 sampling was increased or repeated, then in 75.1% of the instances the habitat extent model is
150 the best model, in 10.3% of cases models the null model is the best model, in 7.9% of cases
151 the sweep net weighted model is best and in 6.7% of cases the Vortis weighted models is
152 best.

153

154 **4. Discussion**

155 Habitat models explained the relationship between tree sparrow fledgling success and the
156 environment more effectively than those that incorporated measures of food availability.
157 Differences in the explanatory power of these models highlight the importance of a model
158 comparison approach when assessing habitat quality.

159

160 Ponce et al. (2014) compared the predictive power of habitat and food models during three
161 bird life stages; breeding, post-fledging and over-wintering. They found that models of bird
162 species-richness, diversity and total abundance during post-fledgling and over-wintering
163 periods were improved by between 13% and 20% by including measures of invertebrate and
164 seed abundance. Like our study, they report that during the breeding season, food weighted
165 models were no better than habitat extent models in predicting responses in the bird
166 community. In their study they highlight the importance of investigating food and habitat
167 models at different points in the annual cycle, however, they do not consider how bird
168 responses may differ throughout a bird's life cycle. Our result shows that when studying
169 reproductive success, a simple habitat measurement such as land area may better describe

170 multiple ecological constraints that limit the use of resources e.g. predation pressure, intensity
171 of competition, and physical accessibility of prey. Additionally, Ponce et al.'s 2014 study was
172 based on analysis of whole bird community responses, but the effectiveness of food and
173 habitat models may differ between individual species depending on their foraging strategies.

174

175 Our finding that the habitat model best fitted the fledging success data was unexpected and
176 there are a number of potential alternative explanations for this result. Firstly, habitat
177 sampling may have taken place on too small a scale and may not be representative of the
178 landscape; more information may have been revealed by increasing our sampling effort.
179 Alternatively, the invertebrate sampling methods used may not have appropriately captured
180 the invertebrate diversity within these habitats or do not accurately represent the foraging
181 behaviour of tree sparrows. Our result may also relate to the timing of invertebrate sampling.
182 Invertebrate samples were taken in late summer; at this time some invertebrates (e.g.
183 Carabidae and Staphylinidae) will have migrated from overwinter refuges in boundaries into
184 crops (Thomas et al., 2001) and aphid populations will have crashed (Karley et al., 2004).
185 Douglas et al., (2009) support this theory and report that the difference in chick food
186 abundance between crop and grass margins was lowest in July. Chick food will still be in
187 peak demand at this time for a number of vulnerable farmland species including the tree
188 sparrow (Ferguson-Lees et al., 2011). If this study were to be repeated, we would recommend
189 collecting more detailed information on seasonal patterns of food availability as this would
190 result in more accurately weighted models.

191

192 Habitat coverage models are currently the most popular means of investigating the potential
193 benefits of AES to birds (e.g. Baker et al., 2012; Bradbury and Allen, 2003; Bright et al.,
194 2015; Davey et al., 2010; Henderson et al., 2012) and although our findings provide some
195 support to this method, we recommend that future studies comparing the explanatory power
196 of food and habitat extent models do so for a variety of species. This will ensure that habitat
197 extent models appropriately describe bird-habitat relationships for different functional groups
198 (granivorous, insectivorous etc; Henderson et al., 2000) and that these models also focus on
199 different stages in a bird's life cycle (e.g. fledgling, post-fledgling). Future studies could also
200 include measures of other ecological constraints, for example vegetation density could be
201 used as a measure of resource accessibility and cover from predators. Additionally, the spatial
202 arrangement of AES habitats could be considered as habitat configuration may be critical for
203 central place foragers such as tree sparrow due to their limited foraging range. This

204 information may be needed to help interpret the responses of bird species to AES
205 interventions and consequently allow more representative evaluations of AES's efficiency.

206

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210

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Table 1. The total number of samples taken from each habitat type is outlined with the number of farms these samples represent displayed in brackets.

Habitat Type	Sweep Net	Vortis
Winter Cereal	44 (9)	12 (3)
Pasture	31 (10)	9 (3)
Oilseed rape	20 (5)	9 (3)
Grass AES	49 (8)	18 (3)
WBSM	15 (5)	6 (2)

Table 2. Results of GLMM models under investigation.

	Covariate	Estimate	Std. Error	Z value	P
Null model	Intercept	0.849	0.197	4.318	<0.001
Habitat model	Intercept	1.661	0.545	3.049	<0.01
	Grass AES	0.695	1.597	0.435	0.664
	OSR	0.276	0.447	0.617	0.537
	WBSM	-2.289	1.149	-1.922	<0.05
	Grassland	-1.503	0.676	-2.225	<0.05
	Winter Cereal	-0.763	0.490	-1.557	0.120
Food model (sweep)	Intercept	1.579	0.559	2.825	<0.01
	Grass AES	0.005	0.055	0.100	0.921
	OSR	0.029	0.036	0.804	0.422
	WBSM	-0.101	0.064	-1.572	0.116
	Grassland	-0.074	0.055	-1.355	0.175
	Winter Cereal	-0.082	0.046	-1.775	0.075
Food model (Vortis)	Intercept	1.618	0.560	2.889	<0.01
	Grass AES	0.001	0.039	0.021	0.983
	OSR	0.019	0.027	0.719	0.472
	WBSM	-0.064	0.044	-1.447	0.148
	Grassland	-0.051	0.038	-1.347	0.178
	Winter Cereal	-0.055	0.028	-1.940	0.052

Table 3. Comparison of alternative models with details of the degrees of freedom (DF), AIC values, differences in AIC values and Akaike weights for all models.

Model	DF	AIC	AIC differences	Akaike weights
Null	6	1507.120	3.968	0.103
Habitat	11	1503.152	0.000	0.751
Food (sweep)	11	1507.652	4.500	0.079
Food (vortis)	11	1507.985	4.833	0.067